

Matlab Implementation of the Enhanced Interval Approach for Encoding Words into Interval Type-2 Fuzzy Sets

Dongrui Wu, Jerry M. Mendel, and Simon Coupland

Matlab implementation of the EIA, proposed in the paper:

Dongrui Wu, Simon Coupland, and Jerry M. Mendel, "Enhanced Interval Approach for Encoding Words into Interval Type-2 Fuzzy Sets and Its Convergence Analysis," submitted to *IEEE Trans. on Fuzzy Systems*, 2011.

is given here so that it can be freely used by other researchers. The input and output parameters are:

- a : left end-points of the data intervals from survey
- b : right end-points of the data intervals from survey
- MF : MF of the word model defined by 9 parameters. For left-shoulder, it is $[0, 0, \bar{a}_{MF}, \bar{b}_{MF}, 0, 0, \underline{a}_{MF}, \bar{b}_{MF}, 1]$. For interior FOU, it is $[\underline{a}_{MF}, \underline{c}_{MF}, \bar{c}_{MF}, \bar{b}_{MF}, \bar{b}_{MF}, \bar{a}_{MF}, p, p, \underline{b}_{MF}, \mu_p]$. For right-shoulder, it is $[\underline{a}_{MF}, \bar{b}_{MF}, M, M, \bar{a}_{MF}, \bar{b}_{MF}, M, M, 1]$
- $nums$: number of remaining intervals after each precessing step
- $shape$: left-shoulder (1), interior (2), or right-shoulder (3)
- FSL : left endpoints of the remaining embedded T1 FSs
- FSR : right endpoints of the remaining embedded T1 FSs

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function [MF, nums, shape, FSL, FSR] = EIA(a,b)

MF=zeros(1,9); nums=zeros(1,8); shape=0; FSL=0; FSR=0; n=length(a);

%% Remove incomplete data intervals
index=find(isnan(a)+isnan(b)); a(index)=[]; b(index)=[];

%% Bad data processing
for i=length(a):-1:1
    if a(i)<0 || a(i)>10 || b(i)<0 || b(i)>10 || b(i)<=a(i) || b(i)-a(i)>=10
        a(i)=[]; b(i)=[];
    end
end
n1=length(a); % n'
if n1==0; return; end

%% Outlier processing
l=sort(a); r=sort(b); n3=floor(n1*0.25); n4=floor(n1*0.75);

% Compute Q(0.25), Q(0.75) and IQR for a
Qa25=l(n3)*(1-rem(0.25*n1,1))+l(n3+1)*rem(0.25*n1,1);
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Dongrui Wu is with the Industrial Artificial Intelligence Laboratory, GE Global Research, Niskayuna, NY 12309 USA (email: wud@ge.com).

Jerry M. Mendel is with the Signal and Image Processing Institute, Ming Hsieh Department of Electrical Engineering, University of Southern California, Los Angeles, CA 90089-2564 USA (e-mail: mendel@sipi.usc.edu).

Simon Coupland is with the Center for Computational Intelligence, De Montfort University, Leicester, LE1 9BH UK (e-mail: simonc@dmu.ac.uk).

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Qa75=l(n4)*(1-rem(0.75*n1,1))+l(n4+1)*rem(0.75*n1,1);
IQRa=Qa75 - Qa25;

% Compute Q(0.25), Q(0.75) and IQR for b
Qb25=r(n3)*(1-rem(0.25*n1,1))+r(n3+1)*rem(0.25*n1,1);
Qb75=r(n4)*(1-rem(0.75*n1,1))+r(n4+1)*rem(0.75*n1,1);
IQRb=Qb75-Qb25;

% Outlier processing for a and b
for i=n1:-1:1
    if a(i)<Qa25-1.5*IQRa || a(i)>Qa75+1.5*IQRa...
        || b(i)<Qb25-1.5*IQRb || b(i)>Qb75+1.5*IQRb
        a(i)=[]; b(i)=[];
    end
end
n2=length(a); % n'
if n2==0; return; end

% Compute Q(0.25), Q(0.75) and IQR for interval length
L=b-a; leng=sort(L); n3=floor(n2*0.25); n4=floor(n2*0.75);
QL25=leng(n3)*(1-rem(0.25*n2,1))+leng(n3+1)*rem(0.25*n2,1);
QL75=leng(n4)*(1-rem(0.75*n2,1))+leng(n4+1)*rem(0.75*n2,1);
IQRL=QL75-QL25;

% outlier processing for interval length
for i=n2:-1:1
    if L(i)<QL25-1.5*IQRL || L(i)>QL75+1.5*IQRL
        a(i)=[]; b(i)=[]; L(i)=[];
    end
end
m1=length(a); % m'
if m1==0; return; end

%% Tolerance limit processing
ma=mean(a); stda=std(a); mb=mean(b); stdb=std(b);
K=[5 4.275 5.079 6.634 6.612 7.855 10.3
   6 3.712 4.414 5.775 5.337 6.345 8.301
   7 3.369 4.007 5.248 4.613 5.488 7.187
   8 3.136 3.732 4.891 4.125 4.936 6.468
   9 2.967 3.532 4.631 3.822 4.550 5.966
   10 2.839 3.379 4.433 3.582 4.265 5.594
   11 2.737 3.259 4.277 3.397 4.045 5.308
   12 2.655 3.162 4.150 3.250 3.870 5.079
   13 2.587 3.081 4.044 3.130 3.727 4.893
   14 2.529 3.012 3.955 3.029 3.608 4.737
   15 2.480 2.954 3.878 2.945 3.507 4.605
   16 2.437 2.903 3.812 2.872 3.421 4.492
   17 2.400 2.858 3.754 9.808 3.345 4.393
   18 2.366 2.819 3.702 2.753 3.279 4.307
   19 2.337 2.784 3.656 2.703 3.221 4.230
   20 2.310 2.752 3.615 2.659 3.168 4.161
   25 2.208 2.631 3.457 2.494 2.972 3.904

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30 2.140 2.549 3.350 2.385 2.841 3.733
35 2.090 2.490 3.272 2.306 2.748 3.611
40 2.052 2.445 3.213 2.247 2.677 3.518
45 2.021 2.408 3.165 2.200 2.621 3.444
50 1.996 2.379 3.126 2.162 2.576 3.385
60 1.958 2.333 3.066 2.103 2.506 3.293
70 1.929 2.299 3.021 2.060 2.454 3.225
80 1.907 2.272 2.986 2.026 2.414 3.173
90 1.889 2.251 2.958 1.999 2.382 3.130
100 1.874 2.233 2.934 1.977 2.355 3.096
150 1.825 2.175 2.859 1.905 2.270 2.983
200 1.798 2.143 2.816 1.865 2.222 2.921
250 1.780 2.121 2.788 1.839 2.191 2.880
300 1.767 2.106 2.767 1.820 2.169 2.850];
[temp,index]=min(abs(K(:,1)-m1));
k=K(index,2); % gamma=0.05, alpha=0.1

% Tolerance limit processing for a and b
for i=m1:-1:1
    if a(i)<ma-k*stda || a(i)>ma+k*stda || b(i)<mb-k*stdb || b(i)>mb+k*stdb
        a(i)=[]; b(i)=[]; L(i)=[];
    end
end
mplus=length(a); % m*
if mplus==0; return; end

% Tolerance limit processing for interval length
mL=mean(L); stdL=std(L);
[temp,index]=min(abs(K(:,1)-mplus));
k=min([K(index,2),mL/stdL,(10-mL)/stdL]);
for i=mplus:-1:1
    if L(i)<mL-k*stdL || L(i)>mL+k*stdL
        a(i)=[]; b(i)=[]; L(i)=[];
    end
end
m2=length(a); %m''
if m2==0; return; end

%% Reasonable interval processing
ma=mean(a); stda=std(a); mb=mean(b); stdb=std(b);

% Determine xi*
if stda==stdb
    xi=(ma+mb)/2;
elseif stda==0
    xi=ma+0.0001;
elseif stdb==0
    xi=mb-0.0001;
else
    xi1=(mb*stda^2-ma*stdb^2+stda*stdb*sqrt((ma-mb)^2 ...
+2*(stda^2-stdb^2)*log(stda/stdb)))/(stda^2-stdb^2);
    xi2=(mb*stda^2-ma*stdb^2-stda*stdb*sqrt((ma-mb)^2 ...

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+2*(stda^2-stdb^2)*log(stda/stdb)))/(stda^2-stdb^2);
if xi1>=ma && xi1<=mb
    xi=xi1;
else
    xi=xi2;
end
end

% Reasonable interval processing
for i=m2:-1:1
    if a(i)>=xi || b(i)<=xi || a(i)<2*ma-xi || b(i)>2*mb-xi
        a(i)=[];      b(i)=[];      L(i)=[];
    end
end
m=length(a);
if m==0; return; end

%% Admissible region determination
tTable=[5 1.476 2.015 3.365
       6 1.440 1.943 3.143
       7 1.415 1.895 2.998
       8 1.397 1.860 2.896
       9 1.383 1.833 2.821
      10 1.372 1.812 2.764
      11 1.363 1.796 2.718
      12 1.356 1.782 2.681
      13 1.350 1.771 2.650
      14 1.345 1.761 2.624
      15 1.341 1.753 2.602
      16 1.337 1.746 2.583
      17 1.333 1.740 2.567
      18 1.330 1.734 2.552
      19 1.328 1.729 2.539
      20 1.325 1.725 2.528
      21 1.323 1.721 2.518
      22 1.321 1.717 2.508
      23 1.319 1.714 2.500
      24 1.318 1.711 2.492
      25 1.316 1.708 2.485
      26 1.315 1.706 2.479
      27 1.314 1.703 2.473
      28 1.313 1.701 2.467
      29 1.311 1.699 2.462
      30 1.310 1.697 2.457
      40 1.303 1.684 2.423
      50 1.299 1.676 2.403
      60 1.296 1.671 2.390
      80 1.292 1.664 2.374
     100 1.290 1.660 2.364
    1000 1.282 1.646 2.330];
[temp,index]=min(abs(tTable(:,1)-m+1));
t=tTable(index,3); ml=mean(a); mr=mean(b) ;

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c=b-5.831*a; d=b-0.171*a-8.29;
tc=t*std(c)/sqrt(m); td=t*std(d)/sqrt(m);
FSL=zeros(1,m); FSR=zeros(1,m);

%% Establish nature of FOU
if mr>5.831*ml-tc && mr<.171*ml+8.29-td
    for i=m:-1:1 % lef-shoulder
        FSL(i)=0.5*(a(i)+b(i))-(b(i)-a(i))/sqrt(6);
        FSR(i)=0.5*(a(i)+b(i))+sqrt(6)*(b(i)-a(i))/3;
        % Delete inadmissible T1 FSs
        if FSL(i)<0 || FSR(i)>10
            FSL(i)=[]; FSR(i)=[];
        end
    end
    shape=1; m0=length(FSL);
    if m0==0; return; end
    UMF=[0, 0, max(FSL), max(FSR)];
    LMF=[0, 0, min(FSL), min(FSR), 1];
elseif mr<5.831*ml-tc && mr>.171*ml+8.29-td
    for i=m:-1:1 % right-shoulder
        FSL(i)=0.5*(a(i)+b(i))-sqrt(6)*(b(i)-a(i))/3;
        FSR(i)=0.5*(a(i)+b(i))+(b(i)-a(i))/sqrt(6);
        % Delete inadmissible T1 FSs
        if FSL(i)<0 || FSR(i)>10
            FSL(i)=[]; FSR(i)=[];
        end
    end
    shape=3; m0=length(FSL);
    if m0==0; return; end
    UMF=[min(FSL), min(FSR), 10, 10];
    LMF=[max(FSL), max(FSR), 10, 10, 1];
else
    for i=m:-1:1 % Interior FOU
        FSL(i)=0.5*(a(i)+b(i))-sqrt(2)*(b(i)-a(i))/2;
        FSR(i)=0.5*(a(i)+b(i))+sqrt(2)*(b(i)-a(i))/2;
        % Delete inadmissible T1 FSs
        if FSL(i)<0 || FSR(i)>10
            FSL(i)=[]; FSR(i)=[];
        end
    end
    FSC=(FSL+FSR)/2;
    L1=min(FSL); L2=max(FSL); R1=min(FSR); R2=max(FSR);
    C1=min(FSC); C2=max(FSC); shape=2; m0=length(FSL);
    if m0==0; return; end
    hs=zeros(1,m0*(m0-1));
    for i=1:m0
        hs((i-1)*m0+(1:m0))=(FSR(i)-FSL)./(FSR(i)-FSL+FSC-FSC(i));
    end
    [h,index]=min(hs);
    i=ceil(index/m0); j=index-(i-1)*m0;
    p=FSL(j)+h*(FSC(j)-FSL(j));
    UMF=[L1, C1, C2, R2]; LMF=[L2, p, p, R1, h];
end

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end

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MF=[UMF LMF];  
nums=[n n1 n2 m1 mplus m2 m m0];
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